Control Unit Operational Diagram F19.1 **GPS** 10 -14 18 20 -INSTRITO ROVER -STR. TO ROVER CELLULAR POWER ON CONTROLER ROVER POSMON TRANSCEIVER DIGITAL -ROVER POSITION COMPASS RECEIVER POWER ON TRANSCEIVER IS PROGRAMMED WITH ROVER CELL NUMBERS OPERATION MODE: STAND BY FIND MY LOCATION PHONE BEEPER OFF GRAPHICAL MODE: SEARCH MAP Breed Crumb MESSAGE TO ROVER: SEND(#1) STAND DOWN((#0) CATA(MAP) MAPPING MODULE POSITION MODULE DISPLAY

SEARCH SCREEN

MAP SCREEN

POWER ON

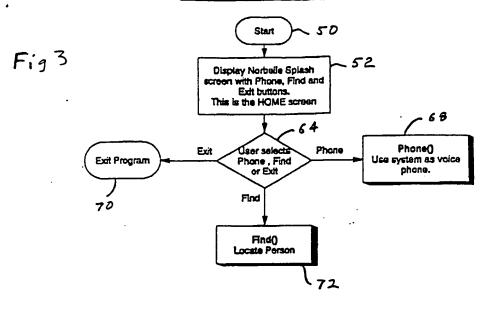
PANIC BUTTON

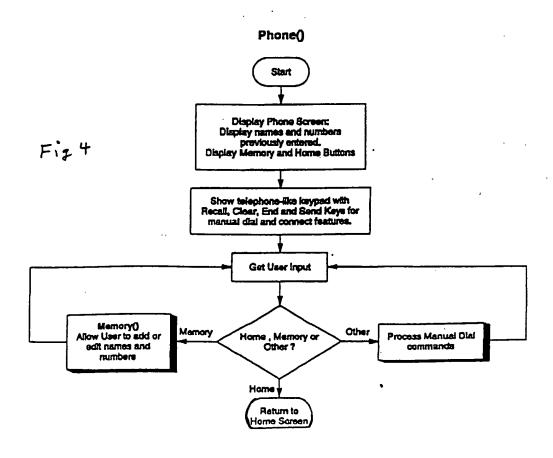
GPS Fig 2 CONTROLER CONTROL INSTRUCTIONS CELLULAR TRANSCEIVER POSITION TO CONTROL POSITION TO CONTROL POSITION TO CONTROL

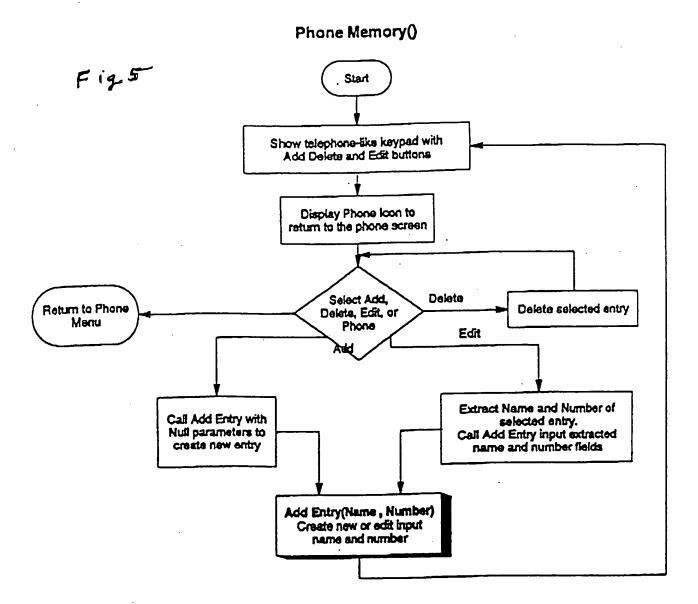
TRANSCEIVER IS PROGRAMMED WITH

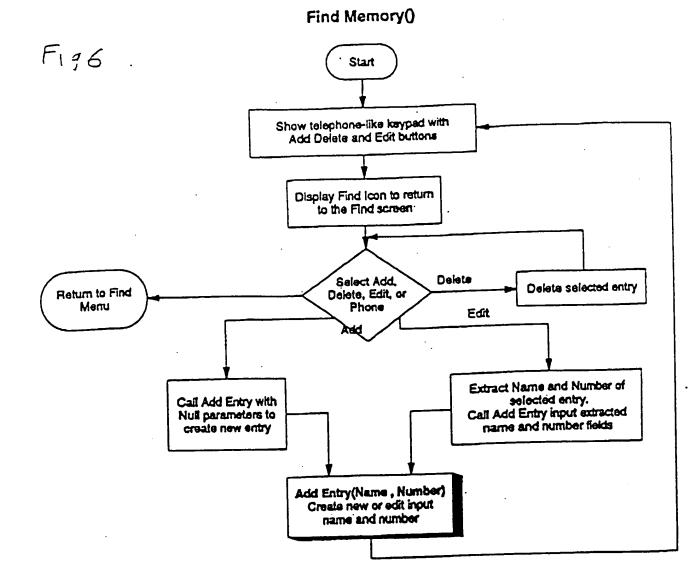
CONTROL UNITS' NUMBER

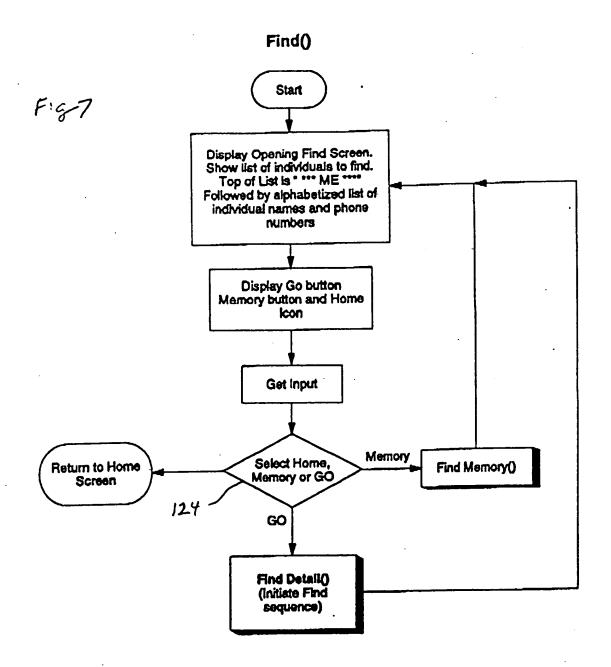
Norbelle in Touch Controller

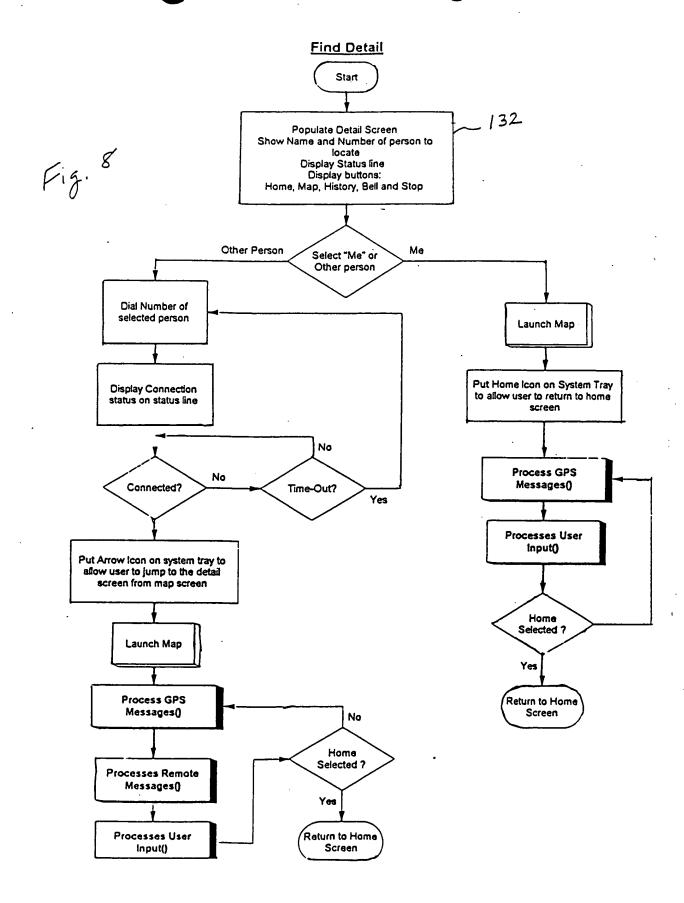


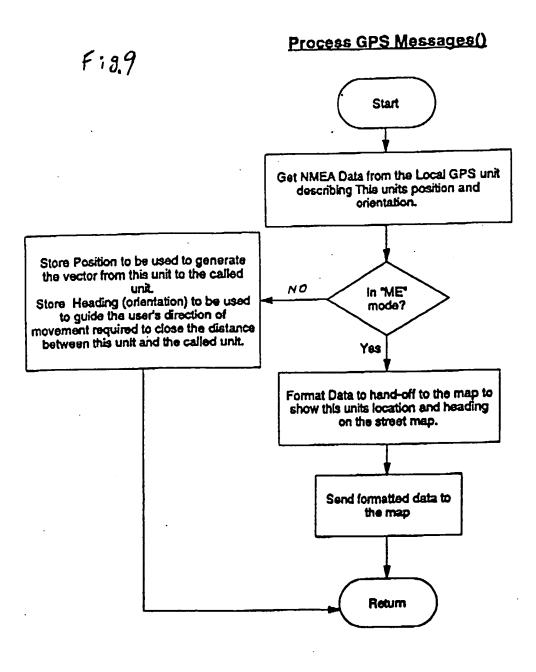




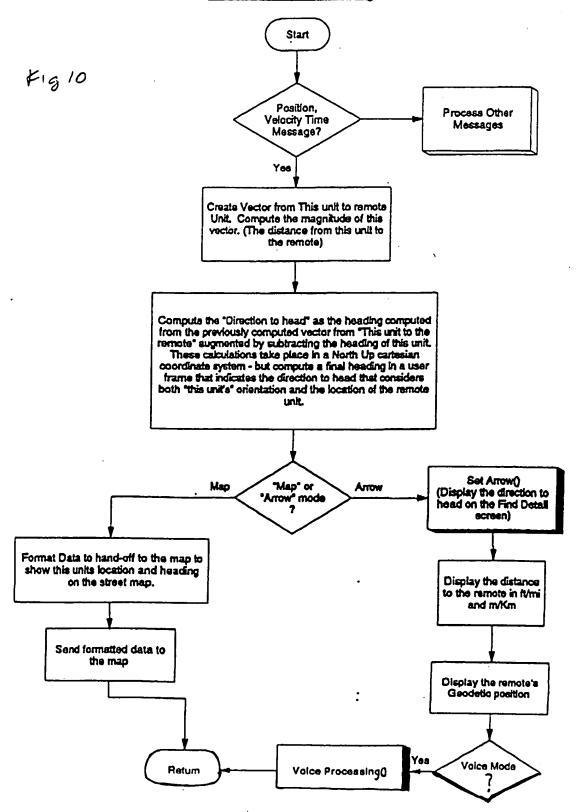


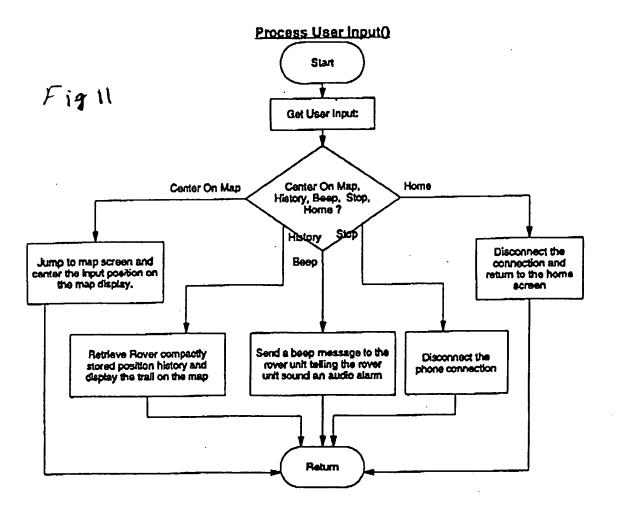


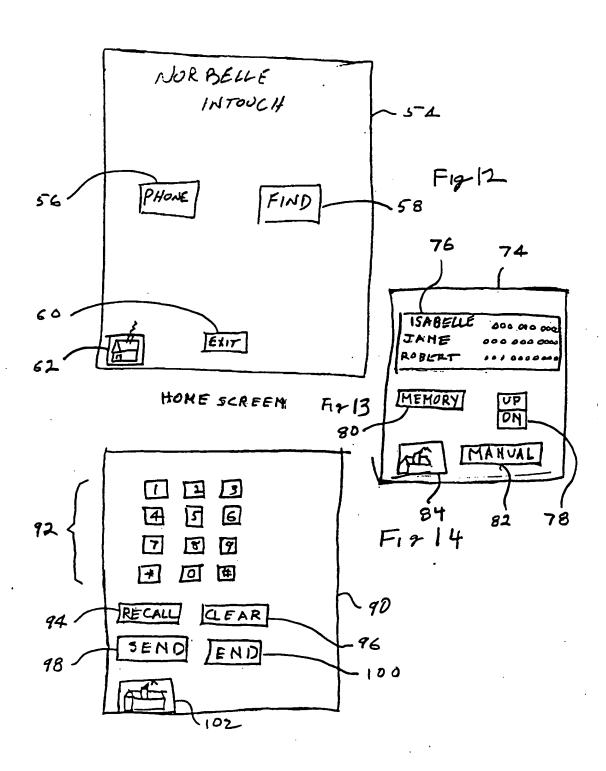


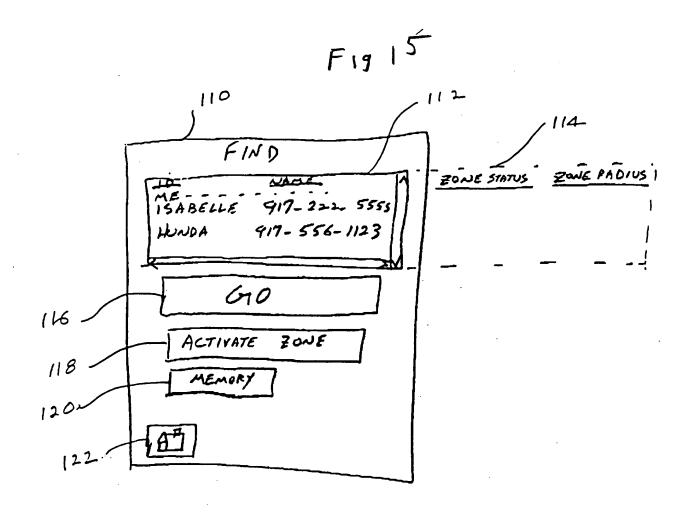


Process Remote Messages

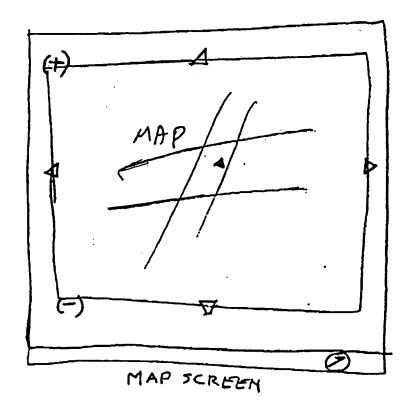








	/130	
	FIND DETAIL	7
	13 ABELLE 10: 417-121-5555	134
	DIST: YEX MI SPEED: ARE MYAY SPEED: ARE MYAY SAY Kunfay	
	HT: XXY FT TIME: XXX; SAR	
	LAT LONG ELEY.	- Va
5:	PATUS:	Fig. 16
	HOME CENTER BREAD CRUMB (F) (F) (F) (F) (F) (F)	
	FIND DETAIL SCREET	



F12.17